

## **EEIG ERTMS Users Group**

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## **ERTMS USERS GROUP - ENGINEERING GUIDELINE**

## HTD Engineering Guideline -Traceability Matrix against X2R Moving Block ENG Rules

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Version	Date	Comments	Author
0a	25/10/2021	First draft (presented at ESG94)	EUG
0b	24/11/2021	Update after ESG94 and ESG ad-hoc meeting 05/11/2021	EUG
0c	16/12/2021	Alignment with L3 Engineering guideline version 1d and update after ESG95	EUG
0d	23/12/2021	Alignment with L3 Engineering guideline version 2-	EUG
1-	23/12/2021	First finalised version and alignment with L3 Engineering guideline 2-	EUG
1a	28/10/2022	Update of traceability matrix according to Version 9 of X2R- 5 engineering rules and L3 Engineering guideline version 2b	EUG
1b		Update of traceability matrix according to Version 10 of X2R-5 engineering rules and L3 Engineering guideline version 2c	EUG
		Adjustments of references after comments ESG104 meeting to HTD guideline version 2c	EUG
2-	19/12/2022	Finalised version 2 Alignment with HTD guideline version 3-	EUG

		Engineering Rules X2R5			(L3 Engineering guideline)	(HTD Engineering guideline)
	Modifications of X2R5	ENG rules since the publication of	version 2 of the EUG guideline are marked in red			
Engineering Rule	Description	Rationale	Guidance Requirem	Update Oct 22 ents (version 10)	Content version 2-	Content version 3-
ENG-Generic-1	The L3 Trackside shall be configured to update a	a On a Level 3 Moving Block railwa h the End of Authority (EoA) can b	y A specific minimum distance for MA extension should be REQ-MA-9 e established, as well as a minimum time interval to send an e update. Where this constraint is not required the distance		Covered by 4.4.1.5	4.4.1 deleted
ENG-Generic-2		a the End of Authority can be at a arbitrary location on the tracl Therefore, depending on th application, rules may be require to avoid trains stopping in area	y Examples include avoiding MAs that end inside a tunnel, REQ- n over a level crossing, junctions or any other areas where EoAExclusion . stopping a train is considered undesirable from a safety or e operational perspective. Where it is unacceptable for a train d to stop with a pantograph in a powerless section, the s engineering of the EoA Exclusion areas should take r account of potential positions of the pantograph. Projects may also consider configuration of Non-Stopping Areas for End of Authority Exclusion Areas. Note: Non-stopping areas transmitted by ETCS only provide information to the driver.	Area-1	Covered by 4.4.1.2	4.4.1 deleted
ENG-Generic-3	and convergences where the rear of a train, including	g to release points as soon as f train has cleared them. Th		Removed	Problem description is covered by 4.3.2.1. Solution is proposed in 4.3.5.1.	
ENG-Generic-3	length of an Unknown Track Status Area that can be safely cleared by the L3 Trackside without sweeping o visual inspection.	e short lengths of an Unknow r Track Status Area left due t differences in the reported trai length after shunting, splitting of		tus-12 Formerly: ENG- Generic-4	Covered by 4.2.13.9	Covered by 4.2.13.9
ENG-Generic-4	train is required to avoid operational impact, the L Trackside engineering shall consider project specifi mitigations to manage the location error within trai position reports.	3 operational performance of th c line due to the assumed train position locking points of crossings.	e This is project specific but could include, for example, the REQ-TTD-3 e use of TTD around points or complex switching and n crossings or having balise groups close enough to the End or of Mission areas to minimise the confidence interval in train position reporting to the L3 Trackside. This may apply where trains regularly undertake End of Mission or stop at platforms or in loops with a requirement for other trains to pass or use other routes. In deciding whether to provide extra facilities, consideration should be given to the likelihood that a train is unable to report integrity confirmed.	Formerly: ENG- Generic-5	Use of TTD is covered by 4.2.5.7. The used of balise groups to reduce the confidence interval is explained in 4.2.6. & 4.2.6.3	Use of TTD is covered by 4.2.5.7. The used of balise groups to reduce the confidence interval is explained 2 in 4.2.6.2 & 4.2.6.3
ENG-Generic-5	The IM shall establish the length of a "L3 Margin" to be used between trains.	move before the ETC supervision stops them. This ca occur intentionally or accidentally Use of the L3 Margin defined i this Rule enables reduction of th			Covered by 4.2.5.3	Covered by 4.2.5.3
ENG-Generic-6	application specific rules for establishing when	e when using FVB depends on th of operational needs of the railway.	n The design should take account of the required train REQ-FVB-1 e movements including where End of Mission and Start of Mission will occur, where splitting and joining may occur and the required capacity of the railway.	Formerly: ENG- Generic-7	Very generic clause. No need to address it in the guideline.	Very generic clause. No need to address it in the guideline.
ENG-Generic-7	Unknown Track Status Area created due to a faulty TTI may be treated as Clear following sweeping or othe checks.	D the area will be considered a r Unknown Track Status eve though the L3 trackside may be able to monitor the passage of trains using Position Report. Since TTD is often provided for degraded scenarios where th	e	Formerly: ENG- Generic-8	Covered by 4.3.1.2	Covered by 4.3.1.2
ENG-Generic-8	The L3 Trackside shall be configured, where possible to use Balise Linking Information.	improves the accuracy of trai positioning, fundamental to the L	n It is expected that Balise Linking Information will be used in REQ-MA-11 n Level 3 areas. 3 It is recommended to set a linking reaction for the first n expected Balise Group in the linking chain when authorising trains to move which will brake the train if it is not found as expected.	Formerly: ENG- Generic-9	Covered by 4.2.6.2	Covered by 4.2.6.2

		Engineering Rules X2R5			(L3 Engineering guideling	e) (HTD Engineering guideline)
	Modifications of X2K	ENG rules since the publication of	version 2 of the EUG guideline are marked in red	Update O	t 22	
Engineering Rule ENG-Generic-9		ty to avoid leaving the area behin	Guidance         Requir           d When trains undertake Start of Mission, it is not always REQ-Loss         dopossible to identify their Train Location uniquely. FirstMA-           k Engineering Rules need to define when a train with an unknown position or not reporting integrity confirmed can be authorised to move by the L3 Trackside.         The Infrastructure Manager may decide that trains without integrity confirmed may not be authorised to move until extra controls are in place. The configuration options should include:           Issue an MA irrespective of integrity status, Do not issue an MA when no integrity is confirmed, Only issue an MA when no integrity is confirmed with the Dispatcher's authorisation.			Covered by 4.2.3
ENG-Generic-10		Is Authority issued to a train caus recalculation of the spee supervision on board, and th results are displayed in th planning area. Frequent change to the Movement Authority ca therefore lead to distraction of th Driver. In accordance with 7.4.1. of ERA_ERTIMS_015560, v3.6. [15560], if the train is in Targe Speed Monitoring for the EoA the a sound is played each time th Most Restrictive Displayed Targe is updated. The configuratio should allow the Infrastructur Manager to prevent changes i	D In implementing such limits on the MA update, it will be this important to bear in mind the potential impact this may have non ATO operation (if fitted). Limiting the MA update may eresult in degrading the service due to suboptimal speed it curves being followed. Careful analysis therefore needs to n take place to ensure the impact is minimised. An alternative, e that would require a change to the current ETCS baseline in [BL3 R2], would be to decouple the update of the MA from it the alerts that the Driver receives.	9. Formerly: EN Generic-11	G- Covered by 4.4.3.2	Covered by 4.4.3.2
ENG-Generic-11		or Unintentional movements co to railway vehicles could result i	f A Hazard Analysis will be required to determine the hazards None nasociated with unintentional movements of railway vehicles. The Hazard Analysis will depend on the specific topology of the railway, and whether there is protection (e.g. trap points) or detection (e.g. trackside Train Detection) provided in locations where vehicles are regularly parked or stationary. The Hazard Analysis will depend on the nature of the rolling stock permitted to run on a railway. If the rolling stock can be assured to become stationary in the event of loss of integrity, then additional mitigation may not be required. If the rolling stock includes vehicles which are not assured to become stationary, then additional mitigation may determine that it is necessary to protect the area in rear of the train which has lost train integrity. A potential additional mitigation measure is to implement a propagation of Unknown Track Status is required, it is project specific to define the propagation algorithm, including location, timing and extent. Such an algorithm and so that may also be necessary to protect the area for an algorithm, including location, timing and extent. Such an algorithm and set the analysis may also be necessary to consider propagation across handover boundaries between adjacent L3 Trackside systems.	This was the ENG-LossTI-2		Covered by 5.2.1

	<b>Engineering Rules X2R5</b> Modifications of X2R5 ENG rules since the publication of version 2 of the EUG guideline are marked in red		(L3 Engineering guideline)	(HTD Engineering guideline)
Engineering Rule	Description         Rationale         Guidance         Requirements           The L3 Trackside shall be engineered so that, if an area This functionality enables the L3 Each Infrastructure Manager must decide, in conjunction REQ-MA-8	Update Oct 22 (version 10)	Content version 2-	Content version 3-
	of track within a Reserved Status Area becomes Trackside to react as required if with the Railway Undertakings, which option should be Occupied before the L3 Trackside has authorised a train an area of track within a Reserved chosen. for this Reserved Status Area, it will: Status Areas becomes occupied. a) restrict the Authorisation to the start of the Unknown area or b) not send the authorisation to the train or c) request a decision from the Traffic Management System			
ENG-Trackinit-1	Infrastructure Managers shall select which information is Stored information may no longer in circumstances in which the system cannot be sure that all REQ-Trackini-2; to be stored by the L3 Trackside and establish for how be valid and may require the stored information is still relevant, then either it should REQ-TrainLoc-11 long it can be used safely when the L3 Trackside is re- confirmation. The rules for which be confirmed by the Dispatcher, or all the information initialised. Interview of site-specific Information way be stored and for discarded, and the status of the railway treated as track how long it will be used need to be status Unknown. the subject of site-specific Information may be considered valid, it should be considered whether the information abe used to prevent a potentially obstructed section being declared Clear (due to human error) or whether it will be used to enable the system to establish a section is not obstructed. In the function in the latter a short time period is recommended based on the amount and extent of train movements which may have occurred.		Covered by 4.2.13.8	Covered by 4.2.13.8
ENG-TrackInit-2	The Infrastructure Manager shall configure whether or If Stored Information is used at None         None           not the L3 Trackside shall require confirmation by the Trackside         Initialisation,         REQ-TrackInit-3           Responsible         Person that the trackside initialisation confirmation by the Responsible         Responsible         REQ-TrackInit-3           procedure is complete when using Stored Information.         Person is optional.         Person is optional.         Person is optional.	Requirement REQ- TrackInit-3 added	Covered by 4.2.13.8	Covered by 4.2.13.8
ENG-SoM-1	The Infrastructure Manager shall configure whether or This is used in case the The Dispatcher, following non-harmonised rules, may need REQ-SoM-14 not the L3 Trackside shall alert the TMS/ <del>Dispatcher</del> of a Dispatcher has to take an lo contact the Driver to ensure e.g. where this train is, train which has terminated its communication session additional action to ensure the whether it was a Driver's mistake, etc. without Validated Train Data being received by the L3 track, i.e. extend the Unknown Trackside. Trackside.		Covered by 4.2.3 & 4.2.4	Covered by 4.2.3
ENG-SoM-2	The Infrastructure Manager shall configure whether or In the event of a some failure in The Dispatcher, following non-harmonised rules, may need REQ-TrackStatus- not the L3 Trackside shall alert the TMSDispatcher if a the communication which prevents to contact the Driver to ensure e.g. where this train is, 11, REQ-TrackStatus- train has not report Validated Train Data within a the reception of the Validated whether it was a Driver's mistake, etc. 5; REQ-SoM-14 configurable time. 5; REQ-SoM-14 the Dispatcher can take the needed action so that the			ENG-SoM-2 is a generic rule (not specific for L3). See flowchart Start of Mission, SS-026 5.4.4, S11 comes after A33 or A34.
ENG-LevelTrans-1	The Infrastructure Manager shall engineer a means for This is to prevent a train from This can be done by engineering, such as a small section of REQ-LevelTrans-1 the L3 Trackside to monitor trains entering the L3 Only entering the L3 Only area TTD at the border or other means that are application unnoticed by the L3 Trackside and specific. The provision of TTD either side of the border support establishing track status. allows the L3 Trackside to monitor the progress of trains and confirm that a "ghost" train has not followed an authorised movement. The provision of ballses, which are known to the L3 Trackside, and be used to help establish the correct position of all trains transitioning.		Covered by 4.2.3 & 6.1.7	Covered by 4.2.3 & 6.1.7

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Engineering Rule	Description	Rationale	Guidance	Requirements		Content version 2-	Content version 3-
ENG-HO-1	The furthest balise group(s) in the Accepting area required to be known to the Handing Over RBC shall be placed at a distance from the border not less than the	In compliance with the L2-based ERTMS/ETCS system, a balis group with such an engineerer position allows the Handing Ove RBC to disconnect any reporting train passing the border Furthermore, the foreseen margin could be computed so that the Handing Over RBC is able to	<ul> <li>d The margin could be calculated taking in account at lea the following:</li> <li>d a the maximum speed of the line;</li> <li>r b. the number of position report repetitions defined Appendix A3.1 of SS26 [SS026];</li> <li>c.the frequency of position reports;</li> <li>n d.the frequency of TIMS confirmations.</li> <li>e. Where there are divergences beyond the Handing O border, the extent of the balises known to the Handing O</li> </ul>	ast REQ-HO-2 in ver		Disconnection with the HOV RBC happens when the min safe rear end/CRE of the train passes the RBC-RBC	Disconnection with the HOV RBC happens when the min safe rear end/CRE of the train passes the RBC-RBC border, so no need of additional balise groups in the ACC RBC that orders the disconnection. There is no need for an engineering rule as suggested by S2R.
		confirmed having passed the border with its CRE, which allows it to regard the Handing Over area as Clear. Should the CRE still be localised	s a d				
ENG-05-1	of track within a Reserved Status Area becomes Unknown before the L3 Trackside has authorised a train for this Reserved Status Area, it will <del>either:</del> a) include an OS mode profile for the Unknown Track Status Area or	Trackside to automatical authorise trains to sweep Unknown Areas, thus improving availability of the railway and minimising the workload of the Dispatcher. However, for some railways this functionality may no be desirable as authorisation by a Dispatcher may be preferred.	3 Each Infrastructure Manager must decide, in conjunct y with the Railway Undertakings, which option should o chosen. This may be affected by whether TTD is provid g in some countries, drivers are expected to accept an ( sight movement authority and drive cautiously checking a vehicles or other significant obstructions without has been previously advised. Other countries require the Dri t to be aware of reason for the On- sight movement author a due to knowledge of the timetable, verbal communication text messages or other means.	be ed. Dn- for ver rity	Changed	Covered by 4.2.13.9.1	Covered by 4.2.13.9.1
ENG-EoM-1	of TTD in areas where trains are regularly left without a communication session.	communication will be regarder as Unknown Areas. Even if train: are provided with Cold Movemen Detection, this is only useful onc- the train reconnects and it ma have safety benefits to detect th movement of trains which should not be moved.	a Y 2 1	res the		Covered by 4.2.12.2 & 5.1.1.3	Covered by 4.2.12.2 & 5.1.1.3
ENG-Rev-1 (Optional)		of a train may stop after reversing and thereby avoid collision with other train movements. Project could decide to have multiple fixed boundary locations depending or	d This requirement is optional as the location for a Bound for Reversing could also be calculated dynamically train, e.g. depending on the actual train length. s Figure 60 illustrates the location of the Boundary Reversing, being the end of the area to be protected fn other train movements. The Reversing Distance is how fr may reverse from the reference location. The Revers Margin should consider the lengths of trains permitted reverse and an estimated distance for the trains to brake stop if overpassing the permitted reversing distance.	per for om ain ar it ing to		Covered by 4.2.12.8	Covered by 4.2.12.8

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					Update Oct 22		
Engineering Rule	Description	Rationale	Guidance	Requirements		Content version 2-	Content version 3-
ENG-SH-1		<ul> <li>e predefined areas in whith shunting is allowed. Tempora</li> <li>Shunting Areas can be activate and deactivated as require</li> <li>Shunting Areas are used This is</li> <li>protect shunting activities fro other authorised train movemen and to protect authorised train</li> </ul>	re One possibility could be to pre-configure in the L3 Trackis, to a set of areas where movements in SH mode could tai ny place and allow the TMSDispatcher to activate and lin ed them where needed, thus resulting in larger shunting area d. Infrastructure Managers could restrict the extent of shuntin to areas to areas where corresponding protection means su m as, for example, deralling points, balises with "Danger fits Shunting Information" or TTD are available. A simil in method may be used to manage shunting in Level g however the reliance on train position reports means the shunting has to be more tightly controlled.	e k s. g h h or ar 2,	Changed	Covered by 4.2.12.3	Covered by 4.2.12.3
ENG-LossComms-1		of establish when a train is n providing sufficient train positic reports (possibly due communications failure) in ord to take safe reactions. Sinc communications can be lost ar re-established during nor- operation, a suitable delay	to The timer is restarted whenever a message is received fro tot a train. The timer expires when the configured value on reached without receipt of a further message. If the tim to expires, the L3 Trackside will treat this train as having lo er communications. The value of the mute timer will be long that the variable T_NVCONTACT and less than the d communication session expiry, as defined in [SS026]. Us all of the mute timer in this range permits a faster reaction to is loss of communications between a train and the L de Trackside, when compared with waiting for communicati session expiry. It should be possible to disable the mu timer if detection of communication session expiry sufficient. For the mute timer to be applicabl T_NVCONTACT should not be set to infinity and should t significantly less than the communication expiry sessis time in [SS026], and M_NVCONTACT should not be set 'no reaction'. If the mute timer is not used, then it recommended to have a reaction defined for speci M_NVCONTACT, since then the L3 Trackside will t certain that the train has come to a stop by session expiry.	is 1; REQ- pr LossComms-2 st e e a 3 n n e e s s a c is is is is is is is is is is	5	Covered by 6.1.2	M_NVCONTACT is addressed in 4.2.1.4 and 6.1.3.10 Mute timer is addressed in 6.1.2
ENG-LossComms-2	The Infrastructure Manager shall ensure that the reaction to expiry of the session time (T_NVCONTACT), defined in paramete M_NVCONTACT, is not set to "No Reaction"	er is important the trains come to		REQ-LossComms 1; REQ- LossComms-2.	- New		M_NVCONTACT is addressed in 4.2.1.4 and 6.1.3.10
ENG-LossTI-1		e, Trackside to react when a position report other than 'No integri		LossTI-5; REQ-LossT 6 0		Covered by 6.1.4	Covered by 6.1.4

		Engineering Rules	X2R5			(L3 Engineering guideline)	(HTD Engineering guideline)
	Modifie	cations of X2R5 ENG rules since the public	ation of version 2 of the EUG guideline are mark	ed in <mark>red</mark>			
					Update Oct 22		
Engineering Rule	Description	Rationale	Guidance	Requirements	(version 10)	Content version 2-	Content version 3-
ENG-LossTI-2	The Infrastructure Manager shall detern not additional mitigation measures a protect against hazards arising fror movements of railway vehicles.	re required to railway vehicles could	ents of A Hazard Analysis will be required to t result in associated with unintentional mo vehicles. The Hazard Analysis will depend on it the railway, and whether there is prote or detection (e.g. Trackside Train E locations where vehicles are requirally The Hazard Analysis will depend on it slock permitted to run on a railway. I be assured to become stationary in integrity, then additional mitigation m the rolling stock includes vehicles whi become stationary, then the analysis is necessary to protect the area in r has lost train integrity. A potential additional mitigation men propagation algorithm for Unknown Track SI project specific to define the pr including location, timing and extent. If propagation of Unknown Track SI also be necessary to consider propag boundaries between adjacent L3 Track	rements of railway respective topology of othen (e.g. trap points) telection) provided in parked-or-stationary. resolution of the rolling is the rolling stock can the event of loss of y not be required. If ch are not assured to may determine that it ear of the train which ure is to implement a ack-Status-areas- stus is required, it is opegation algorithm, uch an algorithm may us is required, it may tion acress handover	This is now ENG- Generic-12	Covered by 5.2.1	
ENG-LossTI-2		nfigure the L3 Confirmation of integrit integrity by the Driver introduces risk in System, in terms of both the Driver preform procedure and the risk confirmed incorrectly. Trackside is specified	to the L3 the risk of ing the of it being The L3	REQ-TrainLoc-6, REQ_TrackStatu 4.	Formerly ENG- s- LossTI-3	Covered by 3.1.1.5 & 3.4.1.3	Covered by 3.1.1.6 & 3.4.2.1.2
ENG-LossTI-3	L3 Trackside authorises a Movement Au a train reporting 'loss of integrity' or a tra	ure whether the Movement of a trair thority either for integrity within the L3 a ain reporting 'No have significant impac nger than the operational availability. situations, however it	without If the L3 Trackside is configured not the rea could a train unable to confirm integrit to on the operational difficulties since this may in some from being moved to a siding – o may be disrupting operations. Therefore, pro- p move a apply this rule only for certain areas to	y, this could cause prohibit a failed train bstructing traffic and vjects may decide to	Formerly ENG- LossTI-4	Covered by 4.3.4 & 5.2.1.2	Covered by 4.3.4 & 5.2.1.2
ENG-LossTI-4	reports loss of integrity, or when there loss of integrity due to the integrity wai	is an assumed requirements, the L3 it timer expiring, can be configured to ta project specific reaction including updat allow the train to reach t the MA without extendir	Especific In considering whether to send Trackside message the movement of the train ke a safe and whether passengers or staff me e the MA, due to an emergency stop or collision he end of the train. In particular sending an eme gg it, stop should be avoided if the train is g other potentially, greater hazard. The Infrastructure manager may confi to utilise additional information (e.g. re determine if the Loss of Integrity Intentional Loss of Integrity will occu train is split as part of an operat unintentional loss of integrity could be coupling breaking, or a failure of the T The reaction of the L3 Trackside differently depending on the outcome a reaction if the Loss of Integrity is con It is important to note though that a re may be part of an intentional splitting reaction taken by the L3 Trackside ne with operational performance.	should be considered y be exposed to risk of the divided parts of rgency stop message in RV to escape a, gure the L3 Trackside ported train speed) to s intentional or not. for example when a ional procedure. An for example the train MS equipment. may be configured of this – eq. only take sidered unintentional. ported loss of Integrity operation, and so any	- Change - Formerly ENG- LossTI-4	Covered by 4.2.12.4.3 & 4.2.13.7	Covered by 4.2.12.4.3 & 4.2.13.7

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		Update Oct 2		
Engineering Rule		quirements (version 10)	Content version 2-	Content version 3-
ENG-MovSR-1	The Infrastructure Manager shall determine the SR Authorisation is required in The operational advantage of moving trains in SR is that it is RE maximum distance for SR Authorisation the L3 order to move trains without a possible to move trains in degraded situations. Long RE Known Location. All train distances for SR Authorisation may increase the risk of RE movements in SR must be operational errors. This is similar in L2; however, the risk is RE movements in SR must be operational errors. This where there may not be TTD to Managers may determine that detect a train that has overpassed its intended stopping limiting the distance for SR location. Authorisation reduces risk of operational errors.	Q-Reserved-2; Q-MovSR-1;	Covered by 4.2.12.1.2	Covered by 4.2.12.1.2
ENG-FVB-1	For systems with FVB, the L3 Trackside shall be Release Points are used to It is project specific whether the points area which is also an RE engineered such that an FVB boundary is at each release infrastructure such that it EoA Exclusion area is covered by a single FVB. Release point. Can be used for another route. It is therefore logical for these locations to align with the	Q-PTS-2	Covered by 5.1.2.2	Covered by 5.1.2.2
ENG-FVB-2	For systems with FVB, the L3 Trackside shall be The L3 Trackside only supervises None No engineered such that an FVB boundary is at a boundary the Track Status within its of the L3 Area. boundaries.	ne	Covered by 5.1.2.2	Covered by 5.1.2.2
ENG-FVB-3	For systems with FVB and without TTD, the L3 The L3 Trackside only needs to With this engineering rule, the boundaries of the FVB will be No Trackside shall be engineered such that a Radio Hole is supervise a Radio Hole as one aligned with the Radio Hole boundaries. covered and aligned with a single FVB. FVB section, as only one train will	ne Change	Covered by 4.2.13.5.2 & 4.2.13.5.3	Covered by 4.2.13.5.2 & 4.2.13.5.3
ENG-FVB-4	For a system using Fixed Virtual Blocks, these shall be To enable a mixture of trains It is still possible to further subdivide a TTD section into No engineered to align the Trackside Train Detection operating in Level 3 and legacy several Virtual Blocks for use with trains operating in Level system boundaries with the Fixed Virtual Block trains to operate on a line, the L3 3. boundaries. Trackside needs to be able to combine the reports received from trains reporting integrity confirmed with information received from the Trackside Train Detection and to enable consistent movement authorisations to be issued. This minimises the risk of trains that are unknown to the Level 3	ne	Covered by 1.2.1.5 & 1.2.1.7. The alignment of fixed virtual blocks and the TTD borders are not explicitly mentioned, because the guideline already refers to the HL3 concept for the fixed virtual block.	The HTD guideline is based on the HTD concept, which covers by default the system using TTD information and virtual subsections.
ENG-TTD-1	For a system with Trackside Train Detection, the L3 For a system with Trackside Train As with engineering for a L2 scheme, consideration needs RE Trackside shall be engineered, where possible, such Detection, the L3 Trackside shall be taken with the location of TTD boundaries relative to that a TTD boundary is at each Release point at a set of be engineered, where possible, the fouling point to account for vehicle overhang. such that a TTD boundary is at Note that projects may have additional constraints in the each Release point at a set of trackside engineering that may prevent aligning the TTD points. bundaries with the Release Point location. For example, there may be existing TTD located on the track which cannot be re-engineered so that the Release points are exactly aligned.	Q-PTS-2	Covered by 3.1.1.5	Covered by 5.1.2.2
ENG-PTS-1	The Infrastructure Manager shall engineer Release Points will remain locked until a The Release Points must be at or beyond the Fouling Points Red for the divergences, and at or beyond the Point Toe for proconvergences, as shown in Figure X below. In order to determine the value of value of *X* as shown in Figure X, consideration should be given to the risk of rollback of a train which is stationary, with its rear at a Release Point Toe. The area bounded by the Release Point will be similar to that which would be bounded by TTD in a traditional signalling system. For a system with Fixed Virtual Blocks, the Release Points will define Fixed Virtual Block boundaries.		Covered by 4.4.4	4.4.4.3 is intentionally deleted. Concept of overhang is addressed in 4.2.5.8 and recommendation of TTD borders is given in 5.1.2

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	Modifications of X2R5	ENG rules since the publication of v	version 2 of the EUG guideline are marked in red				
Engineering Rule	Description	Rationale	Guidance	Requirements	Update Oct 22 (version 10)	Content version 2-	Content version 3-
			For a system with TTD, if there is a TTD over the Points, this		(,		
ENG-PTS-2	The Infrastructure Manager shall engineer Release Points for Crossings in the L3 Area, to define wher Crossings will be released after the passage of a train.	n using in one sense only, until a	will provide the locking and release. r The Release Points must be at or beyond the Fouling Points a for the divergences, as shown in Figure Y below.	Requirements; REQ PTS-1, REQ-PTS-2		Covered by 4.4.4	4.4.4.3 is intentionally deleted. Concept of overhang is addressed in 4.2.5.8 and recommendation of TTD borders is given in 5.1.2
			In order to determine the value of value of "X" as shown in Figure X, consideration should be given to the risk or rollback of a train which is stationary, with its rear at a Release Point. The area bounded by the Release Point will be similar to that which would be bounded by TTD in a traditiona signalling system. For a system with Fixed Virtual Blocks, the Release Points will define Fixed Virtual Block boundaries. For a system with TTD, if there is a TTD over the Crossing this will provide the locking and release.	f 1 1			
ENG-PTS-3		f successfully confirms that part o	s The Sweeping Points must be at or beyond the Fouling f Points for the divergences, and at or beyond the Point Tos s for convergences. The Sweeping Points must also be at o within the area defined by Release Points. This is shown in Figure Z below.	PTS-4		Covered by 4.2.13.9	Covered by 4.2.13.9
			This distances between the Fouling Points and the Sweeping Points, and between the Sweeping Points and the Release Points may depend on the Operational Rules for driving with an On Sight Mode Profile.			Covered by 4.2.13.9.3	Covered by 4.2.13.9.3
ENG-PTS-4	Points for Crossings in the L3 Area, to define the exten	t successfully confirms that part o	s The Sweeping Points must be at or beyond the Fouling f Points. The Sweeping Points must also be at or within the sarea defined by Release Points. This is shown in Figure 2 below. This distances between the Fouling Points and the Sweeping Points, and between the Sweeping Points and the Release Points may depend on the Operational Rules fo driving with an On Sight Mode Profile.	PTS-4		Covered by 4.4.4.3	Covered by 4.2.13.9.3
ENG-PTS-5	Sweeping Points are within the Release Points Locking Area, the Infrastructure Manager shall determine	the case that the Sweeping Points are within the Release Points, the	When the Sweeping Points are within the Release Points, a small area of Unknown Track Status Area may remain within the area defined by the Release Points. This would I result in the points being locked, and therefore requiring ar s override to be moved.	PTS-5	- Change	Covered by 4.2.13.9 & 4.4.4	Covered by 4.2.13.9 & 4.4.4
ENG-RadioHole-1	The Infrastructure Manager shall engineer the conditions for considering a train to be inside a Radie Hole.	This is required for the La		REQ-RadioHole- 4; REQ-RadioHole 8-		Covered by 4.2.13.5.1	
ENG-RadioHole-12		e system fails, the Dispatcher needs	s The allocation of these Temporary Radio Holes depends or s the communications architecture and likely interruptions to 3 service due to failure. Enabled Radio Holes are treated as f EoA exclusion areas.	o 1.	Number ENG-rule changed	Covered by 4.2.13.6	Covered by 4.2.13.6
ENG-RadioHole-2 <del>3</del>	Radio Hole the time allowed for a train to pass through	n to pass through a Radio Hole the Dispatcher may need to take othe measures to confirm that there	The time could be established automatically or by user o bispatcher input. To avoid unnecessary alerts, the lowes rspeed profile through the area is used reduced by 20% to allow for acceleration, braking and drivability is recommended. When determining the length for a radid hole timer, it must be considered how the L3 trackside determines when a train has entered the radio hole and has left the radio hole. This will be project specific.	t 5 5	Number ENG-rule changed	Covered by 4.2.13.5.4	Covered by 4.2.13.5.4